

Uitwerkingen werkcollege 11.

8.4.1

$$\begin{pmatrix} -1 & 1 \\ 2 & -3 \end{pmatrix}, \quad \begin{pmatrix} 2 & 2 & 1 \\ 1 & 1 & 0 \\ -5 & -4 & -1 \end{pmatrix}, \quad \begin{pmatrix} -3 & -2 & -2 \\ 0 & -1 & 0 \\ 1 & 0 & 1 \end{pmatrix}, \quad \begin{pmatrix} 2 & 0 & -1 & 2 \\ -9 & 1 & 3 & -8 \\ 8 & -1 & -3 & 7 \\ -8 & 1 & 3 & -8 \end{pmatrix}.$$

8.4.4 We use the definition in Definition 5.22: AB is invertible means that f_{AB} is an isomorphism. Then $f_{AB} = f_A \circ f_B: F^n \rightarrow F^n$ is a bijection. Its injectivity implies that $f_B: F^n \rightarrow F^n$ is injective and its surjectivity implies that f_A is surjective. From Corollary 8.5 we then conclude that f_A and f_B are isomorphisms as well, so A and B are invertible as well.

8.4.5 Since I_n is invertible, it follows from Exercise 8.4.4 that M and N are invertible. Note that from $MN = I_n$, we obtain $f_M \circ f_N = \text{id}$, so f_N is a right inverse of the isomorphism f_M . Since every right inverse of a bijection is equal to the inverse of that bijection (see Appendix A), we find that f_N is the inverse of f_M and hence $N = M^{-1}$. It follows that we also have $NM = M^{-1}M = I_n$.

Alternatively, we can use Lemma 8.30. Parts (6) and (7) give that M and N are invertible, and the last statement in Lemma 8.30 says that $M = N^{-1}$ and $N = M^{-1}$. Then $NM = M^{-1}M = I_n$.

8.5.1 For the first three systems we have

$$A = \begin{pmatrix} 2 & 3 & -2 \\ 3 & 2 & 2 \\ 0 & -1 & 2 \end{pmatrix}, \quad \text{with} \quad b = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \quad b = \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix} \quad \text{and} \quad b = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix},$$

respectively. We can reduce the work by extending the matrix A with all three choices for b and finding a reduced row echelon form. The extended matrix is

$$\left(\begin{array}{ccc|ccc} 2 & 3 & -2 & 0 & 1 & 1 \\ 3 & 2 & 2 & 0 & -1 & 1 \\ 0 & -1 & 2 & 0 & -1 & 1 \end{array} \right).$$

and it has reduced row echelon form

$$\left(\begin{array}{ccc|ccc} 1 & 0 & 2 & 0 & -1 & 0 \\ 0 & 1 & -2 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{array} \right).$$

Hence the kernel of A is generated by $a = (-2, 2, 1)$, that is $\ker A = L(a)$. Now for the first b , namely $b = 0$, the solution set is $\ker A = L(a)$. For the second b , if we had extended A by only b , the last column of reduced row echelon form of this extension $(A|b)$ does not have a pivot in the last column, so the system is consistent. We obtain a solution by setting $x = (x_1, x_2, 1)$ and solving for x_1 and x_2 , which gives $x = (-3, 3, 1)$. Therefore, the complete solution space is

$$\{(-3, 3, 1) + z : z \in \ker A\} = \{(-3, 3, 1) + \lambda a : \lambda \in \mathbb{R}\}.$$

For the third b , namely $b = (1, 1, 1)$, the reduced row echelon form of the extended matrix $(A|b)$ has a pivot in the last column, so there is no solution. For the last case, we have

$$A = \begin{pmatrix} 3 & 1 & 2 & -2 \\ 2 & -1 & 2 & 0 \\ 1 & 0 & 1 & 0 \\ -2 & -1 & -1 & 1 \end{pmatrix} \quad \text{and} \quad b = \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \end{pmatrix}.$$

The extended matrix $(A|b)$ has reduced row echelon form

$$\left(\begin{array}{cccc|c} 1 & 0 & 0 & 0 & -13 \\ 0 & 1 & 0 & 0 & 4 \\ 0 & 0 & 1 & 0 & 16 \\ 0 & 0 & 0 & 1 & -2 \end{array} \right).$$

Hence, there is a unique solution, namely $x = (-13, 4, 16, -2)$.

9.1.2 We berekenen de beelden van de elementen van de begin-basis B en schrijven die uit als lineaire combinaties van de elementen van de eind-basis B .

$$T(1) = 3 = 3 \cdot 1 + 0 \cdot x + 0 \cdot x^2 + 0 \cdot x^3 + 0 \cdot x^4$$

$$T(x) = 3x = 0 \cdot 1 + 3 \cdot x + 0 \cdot x^2 + 0 \cdot x^3 + 0 \cdot x^4$$

$$T(x^2) = 3x^2 + (x - 2) \cdot 2 = -4 \cdot 1 + 2 \cdot x + 3 \cdot x^2 + 0 \cdot x^3 + 0 \cdot x^4$$

$$T(x^3) = 3x^3 + (x - 2) \cdot 6x = 0 \cdot 1 - 12 \cdot x + 6 \cdot x^2 + 3 \cdot x^3 + 0 \cdot x^4$$

$$T(x^4) = 3x^4 + (x - 2) \cdot 12x^2 = 0 \cdot 1 + 0 \cdot x - 24 \cdot x^2 + 12 \cdot x^3 + 3 \cdot x^4$$

Dus

$$[T]_B^B = \begin{pmatrix} 3 & 0 & -4 & 0 & 0 \\ 0 & 3 & 2 & -12 & 0 \\ 0 & 0 & 3 & 6 & -24 \\ 0 & 0 & 0 & 3 & 12 \\ 0 & 0 & 0 & 0 & 3 \end{pmatrix}.$$

9.1.3 The map $T: F[x]_{k-1} \rightarrow F^k$ that sends $g \in F[x]_{k-1}$ to $(g(\alpha_1), g(\alpha_2), \dots, g(\alpha_k))$ is an isomorphism by Exercise 8.1.2 (with $n = k - 1$). By Example 9.5, the matrix, say A , associated to T with respect to the basis $B = (1, x, \dots, x^{k-1})$ of $F[x]_{k-1}$ and the standard basis E of F^k is exactly the given Vandermonde matrix. Therefore, the map $f_A: F^k \rightarrow F^k$ is equal to the composition $\varphi_E^{-1} \circ T \circ \varphi_B = T \circ \varphi_B$ of isomorphisms, so it is an isomorphism, and therefore A is invertible.

9.1.4 We geven alleen de uitkomst:

$$\begin{pmatrix} 3 & 0 & 7 & 0 \\ 0 & 3 & 0 & 7 \\ -1 & 0 & 5 & 0 \\ 0 & -1 & 0 & 5 \\ 8 & 0 & 2 & 0 \\ 0 & 8 & 0 & 2 \end{pmatrix}$$

9.2.1 (1)

$$M = [\text{id}]_B^{B'} = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & 2 & 2 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 4 \end{pmatrix} \quad \text{and} \quad N = M^{-1} = \begin{pmatrix} 1 & -\frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{2} & -\frac{1}{3} & 0 \\ 0 & 0 & \frac{1}{3} & -\frac{1}{4} \\ 0 & 0 & 0 & \frac{1}{4} \end{pmatrix}$$

Of course, instead of finding the inverse of M , one can also find N by noticing that $v_1 = v'_1$ and $iv_i = v'_i - v'_{i-1}$ for $2 \leq i \leq 4$.

(2) we have $f_M = \varphi_B^{-1} \circ \text{id} \circ \varphi_{B'} = \varphi_B^{-1} \circ \varphi_{B'}$, so for every $x = (x_1, x_2, x_3, x_4) \in \mathbb{R}^4$ we find

$$Mx = f_M(x) = \varphi_B^{-1}(\varphi_{B'}(x)) = \varphi_B^{-1}(x_1v'_1 + \dots + x_4v'_4) = (x_1v'_1 + \dots + x_4v'_4)_{B'}.$$

(3) Same as (2) with the roles of M and N reversed (as well as the roles of v_i and v'_i).

9.2.2

$$[\text{id}]_E^C = \begin{pmatrix} -1 & -2 & 1 \\ -2 & 1 & -1 \\ 0 & 3 & -2 \end{pmatrix} \quad \text{and} \quad [\text{id}]_C^E = ([\text{id}]_E^C)^{-1} = \begin{pmatrix} 1 & -1 & 1 \\ -4 & 2 & -3 \\ -6 & 3 & -5 \end{pmatrix}.$$